Zubair Irshad

PhD, Research Scientist

Silicon Valley, CA

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Education

PhD - Georgia Institute of Technology, U.S.A

Atlanta, GA

Mechanical Engineering, Specialization: Artificial Intelligence and Deep Learning — *Aug. 2019 - Dec. 2023*

- Advisor: Dr. Zsolt Kira, PI Robotics Perception and Learning Lab
- Thesis: Learning 3D Robotics Perception using Inductive Priors. [Thesis Link, Talk Link]

MS - Georgia Institute of Technology, U.S.A

Atlanta, GA

Mechanical Engineering, Specialization: Robotics — *Aug. 2019 - Dec. 2023*

- CGPA: 3.76/4.0. Relevant Coursework: Robotics, Deep Learning, Machine Learning, Computer Vision, Robotics Research, Interactive Robot Learning, Math. Methods in Applied Sciences, Reinforcement Learning, Visual Perception.

BS - GIK University of Science & Technology

Topi, PK

Mechanical Engineering — *Aug. 2011 - May. 2015*

- CGPA: 3.76/4.0. Graduated with Magna Cum Laude. Awarded Dean honors roll for 8 semesters.

Work Experience

Research Scientist, Toyota Research Institute

Los Altos, CA

Working on Large Behavior Models, 3D Vision and Robotics [16 publications, 8 patents] — *Jan. 2024 - Present*

- Leading and managing various projects on 3D perception and Multimodal AI for Robotics
- Core contributor and co-led multi-task policy learning and post-training for robotics foundational *Large Behavorial model*.
- Managing university collaborations including University of California Berkeley, CMU and others.
- Publications accepted to CVPR, ECCV, CORL, ICRA and IROS. Applied 8 U.S. Patent applicants.

Research Intern, Toyota Research Institute

Los Altos, CA

Led various machine learning vision projects across 3 internships [3 publications, 3 patents] — *May. 2021 - Aug. 2022*

- Innovated single-shot reconstruction and pose estimation (2 papers accepted to ICRA'22, ECCV'22. U.S. patents applied)
- Collaborated with team on fast articulated 3D object reconstruction (Paper accepted to CVPR'22, US Patent applied)

Research Intern, SRI International

Princeton, NJ

Lead a project in the Computer Vision team [1 publication, 1 patent] — *May. 2020 - Aug. 2020*

- Innovated a novel architecture using semantics and spatiotemporal awareness for SOTA Vision-language navigation agent.

Graduate Research Assistant, Georgia Institute of Technology

Atlanta, GA

Successfully led various robotics and machine learning projects [5 publications, 1 patent] — *Jan. 2019 - Dec. 2023*

- Sponsors: Toyota Research Institute, DAPRA Lifelong Learning Machines (*L2M*) and Georgia Tech.
- Led projects on Multimodal AI, Vision-Language, Gaussian Splat Editing, Shape Reconstruction, and 6D pose estimation. Research accepted at ICRA, ICCV, CVPRW.

Publications

[1] J. Barreiros*, A. Beaulieu*, A. Bhat*, R. Cory*, ... **M.Z. Irshad***..., R. Ambrus, K. Fetzer-Borelli, B. Burchfiel, H. Kress-Gazit, S. Feng, S. Ford, R. Tedrake, A Careful Examination of Large Behavior Models for Multitask Dexterous Manipulation, (* **Primary Contributors listed first, alphabetical**), arXiv 2025

[2] V. Guizilini, **M.Z. Irshad**, D. Chen, G. Shakhnarovich, R. Ambrus, Zero-Shot Novel View and Depth Synthesis with Multi-View Geometric Diffusion, Computer Vision and Pattern Recognition, CVPR 2025

[3] S. Iwase, **M.Z. Irshad**, K. Liu, V. Guizilini, R. Lee, T. Ikeda, A. Amma, K. Nishiwaki, K. Kitani, R. Ambrus, S. Zakharov, ZeroGrasp: Zero-Shot Shape Reconstruction Enabled Robotic Grasping, Computer Vision and Pattern Recognition, CVPR 2025

[4] G. Chhablani, X. Ye, R. Grover, **M.Z. Irshad**, Zsolt Kira, EmbodiedSplat: Personalized Real-to-Sim-to-Real Navigation with Gaussian Splats from a Mobile Device, International Conference on Computer Vision, ICCV 2025

[5] S. Lin, J. Fang, **M.Z. Irshad**, V. Guizilini, R. Ambrus, G. Shakhnarovich, M. Walter, SplArt: Articulation Estimation and Part-Level Reconstruction with 3D Gaussian Splatting, International Conference on Computer Vision, ICCV 2025

[6] J. Yu*, K. Hari*, K. El-Refai*, A. Dalal, J. Kerr, C. M. Kim, R. Cheng, **M.Z. Irshad**, K. Goldberg, POGS: Persistent Object Gaussian Splat for Tracking Human and Robot Manipulation of Irregularly Shaped Objects, International Conference on Robotics and Automation, ICRA 2025

[7] A. Jain, M. Zhang, K. Arora, W. Chen, M. Torne, **M.Z. Irshad**, S. Zakharov, Y. Wang, S. Levine, C. Finn, W. Ma, D. Shah, A. Gupta, K. Pertsch, PolaRiS: Scalable Real-to-Sim Evaluations for Generalist Robot Policies, arXiv 2026

[8] **M.Z. Irshad**, S. Zakharov, V. Guizilini, A. Gaidon, Z. Kira, R. Ambrus, NeRF-MAE: Masked AutoEncoders for Self-Supervised 3D Representation Learning for Neural Radiance Fields, European Conference on Computer Vision, ECCV 2024

[9] J. Yu, L. Fu, H. Huang, K. El-Refai, R. A. Ambrus, R. Cheng, **M.Z. Irshad**, K. Goldberg, Real2Render2Real: Scaling Robot Data Without Dynamics Simulation or Robot Hardware, Conference on Robot Learning, CORL 2025

[10] **M.Z. Irshad**, Mauro Comi, Yen-Chen Lin, Nick Heppert, Abhinav Valada, Zsolt Kira, Rares Ambrus, Jonathan Tremblay, Neural Fields in Robotics: A Survey, In Submission, 2025

[11] J. Ye, R. Xue, B. V. Hoorick, P. Tokmakov, **M.Z. Irshad**, Y. W, V. Guizilini, AnchorDream: Repurposing Video Diffusion for Embodiment-Aware Robot Data Synthesis, arXiv 2025

[12] J. Li, H. Wang, **M.Z. Irshad**, I. Vasiljevic, M. R. Walter, V. Guizilini, G. Shakhnarovich, FastMap: Revisiting Dense and Scalable Structure from Motion, International Conference on 3D Vision, 3DV 2026

[13] L. Chen*, C. Xu*, K. Dharmarajan, **M.Z. Irshad**, R. Cheng, K. Keutzer, M. Tomizuka, Q. Vuong, K. Goldberg, RoVi-Aug: Robot and Viewpoint Augmentation for Cross-Embodiment Robot Learning (**Oral Top 4.3%**), Conference on Robot Learning, CORL 2024

[14] T. Ikeda, S. Zakharov, **M.Z. Irshad**, I. B. Opra, S. Iwase, D. Chen, M. Tjersland, R. Lee, A. Dilly, R. Ambrus, K. Nishiwaki, GTR: Gaussian Splatting Tracking and Reconstruction of Unknown Objects Based on Appearance and Geometric Complexity arXiv 2025

[15] Open X-Embodiment Collaboration. A. O'Neill, A. Rehman, A. Gupta,..., **M.Z. Irshad**, *et al.*, Open X-Embodiment: Robotic Learning Datasets and RT-X Models (**Best Paper Award.**), IEEE International Conference on Robotics and Automation, ICRA 2024

[16] T. Ikeda*, S. Zakharov*, T. Ko, **M.Z. Irshad**, R. Lee, K. Liu, R. Ambrus, K. Nishiwaki, DiffusionNOCS: Managing Symmetry and Uncertainty in Sim2Real Multi-Modal Category-level Pose Estimation, IEEE International Conference on Intelligent Robot and Systems, IROS 2024

[17] J. Yu*, K. Hari*, K. Srinivas*, A. Rashid, C. M. Kim, J. Kerr, R. Cheng, **M.Z. Irshad**, A. Balakrishna, T. Kollar, K. Goldberg, LEGS: Incrementally Building Room-Scale Language-Embedded Gaussian Splats with a Mobile Robot, IEEE International Conference on Intelligent Robot and Systems, IROS 2024

[18] A. Khazatsky, K. Pertsch, S. Nair, A. Balakrishna,..., **M.Z. Irshad**, *et al.*, DROID: A Large-Scale In-The-Wild Robot Manipulation Dataset, Robotics: Science and Systems, RSS 2024

[19] J. Yu*, T. Sadjadpour*, A. O'Neill, M. Khfifi, L.Y. Chen, R. Cheng, **M.Z. Irshad**, A. Balakrishna, T. Kollar, K. Goldberg, MANIP: A Modular Architecture for Integrating Interactive Perception for Robot Manipulation, IEEE International Conference on Intelligent Robot and Systems, IROS 2024

[20] M. Lunayach, S. Zakharov, D. Chen, R. Ambrus, Z. Kira, **M. Z. Irshad**, FSD: Fast Self-Supervised Single RGB-D to Categorical 3D Objects, International Conference on Robotics and Automation, ICRA 2024

[21] **M.Z. Irshad**, S. Zakharov, K. Liu, V. Guizilini, T. Kollar, A. Gaidon, Z. Kira, R. Ambrus, NeO 360: Neural Fields for Sparse View Synthesis of Outdoor Scenes, International Conference on Computer Vision, ICCV 2023

[22] N. Heppert, **M.Z. Irshad**, S. Zakharov, K. Liu, R. Ambrus, J. Bohg, A. Valada, T. Kollar, CARTO: Category and Joint Agnostic Reconstruction of Articulated Objects, Computer Vision and Pattern Recognition Conference, CVPR 2023

[23] **M.Z. Irshad***, S. Zakharov*, R. Ambrus, T. Kollar, Z. Kira, A. Gaidon, ShAPO: Implicit Representations for Multi-Object Shape, Appearance, and Pose Optimization, European Conference on Computer Vision, ECCV 2022

[24] **M.Z. Irshad**, T. Kollar, M. Laskey, K. Stone, Z. Kira, CenterSnap: Single-Shot Multi-Object 3D Shape Reconstruction and Categorical 6D Pose and Size Estimation, IEEE International Conference on Robotics and Automation, ICRA 2022

[25] **M.Z. Irshad**, N. Mithun, Z. Seymour, H.P. Chiu, S. Samarasekera, R. Kumar, SASRA: Semantically-aware Spatio-Temporal Reasoning Agent for Vision-and-Language Navigation, International Conference on Pattern Recognition, ICPR 2022

[26] **M.Z. Irshad**, C.Y. Ma, Z. Kira, Hierarchical Cross-Modal Agent for Robotics Vision-and-Language Navigation, IEEE International Conference on Robotics and Automation, ICRA 2021

Thesis, Workshop, and Symposium Publications

[1] X. Zhang, **M.Z. Irshad**, A. Yezzi, Y. Tsai, Z. Kira, EscherNet++: Simultaneous Amodal Completion and Scalable View Synthesis through Masked Fine-Tuning and Enhanced Feed-Forward 3D Reconstruction, 3rd CVPR Workshop on Generative Models for Computer Vision, 2025

[2] G. Chhablani, X. Ye, R. Grover, **M.Z. Irshad**, Zsolt Kira, EmbodiedSplat: Personalized Real-to-Sim-to-Real Navigation with Gaussian Splats from a Mobile Device, CVPR Embodied AI Workshop, 2025

[3] **M.Z. Irshad**, Learning 3D Robotics Perception using Inductive Priors, Doctoral Dissertation, Georgia Institute of Technology, 2023

[4] **M.Z. Irshad**, S. Zakharov, V. Guizilini, A. Gaidon, Z. Kira, R. Ambrus, NeRF-MAE: Masked AutoEncoders for Self-Supervised 3D Representation Learning for Neural Radiance Fields, CVPR Neural Rendering Intelligence Workshop, 2024 and ECCV Scalable 3D Scene Generation and Geometric Scene Understanding, 2024

[5] T. Ikeda, S. Zakharov, T. Ko, **M.Z. Irshad**, R. Lee, K. Liu, R. Ambrus, K. Nishiwaki, Handling Symmetry and Uncertainty in Category-level Pose Estimation with Diffusion Models, ECCV Workshop on Recovering 6D Object Pose, 2024

[6] V. Jaganathan, H. Huang, **M.Z. Irshad**, V. Jampani, A. Raj, Z. Kira ICE-G: Image Conditional Editing of 3D Gaussian Splats, CVPR Workshop on AI for Content Creation, CVPRW 2024

[7] **M.Z. Irshad**, S. Zakharov, R. Ambrus, T. Kollar, Z. Kira, A. Gaidon, ShAPO: Implicit Representations for Multi-Object Shape, Appearance, and Pose Optimization, Baylearn Machine Learning Symposium 2022

Patent Applications

[1] J. Li, H. Wang, **M.Z. Irshad**, I. Vasiljevic, M. R. Walter, V. Guizilini, G. Shakhnarovich. Systems and Methods for Estimating Camera Parameters using Image Data. US Patent App. 19/306,164

[2] V. Guizilini, **M.Z.Irshad**, D. Chen, R. Ambrus. Systems and Methods for Generating a Scaled-Up and Fine-Tuned Diffusion Model for 3D Scene Reconstruction. US Patent App. 19/187,140

[3] V. Guizilini, **M.Z.Irshad**, D. Chen, R. Ambrus. Systems and Methods for Scene Scale Normalization in Multi-View Depth Estimation. US Patent App. 19/187,068

[4] S. Lin, J. Fang, **M.Z.Irshad**, V.C. Guizilini, R.A. Ambrus, G. Shakhnarovich, M. Walter. Systems and Methods for Reconstructing and Rendering Articulated Objects Using 3D Gaussian Splatting. US Patent App. 19/187,006

[5] V. Guizilini, **M.Z.Irshad**, D. Chen, R. Ambrus. Multi-view Geometric Diffusion. US Patent App. 19/184,534

[6] V. Guizilini, **M.Z.Irshad**, D. Chen, R. Ambrus. Multi-view Geometric using Incremental Conditioning. US Patent App. 19/184,592

[7] **M.Z.Irshad**, S. Zakharov, V.Guizilini, A.Gaidon, Z.Kira, R. Ambrus, Performing a three-dimensional Computer Vision task using a Neural Radiance Field grid representation of a scene produced from two-dimensional images of at least a portion of the scene. US Patent App. 19/010,943

[8] V. Guizilini, **M.Z.Irshad**, D. Chen, R. Ambrus. Zero-Shot Novel View and Depth Synthesis with Multi-View Geometric Diffusion. US Patent App. 63/737,994

[9] M. Lunayach, S. Zakharov, D. Chen, R. Ambrus, Z. Kira **M.Z.Irshad**. Fast Self-Supervised Single Image to Categorical 3D Objects Machine Learning Model Training. US Patent App. 18/585,908

[10] N.Heppert, **M.Z.Irshad**, S. Zakharov, K.Liu, R.Ambrus, J.Bohg, T.Kollar. Category and Joint Agnostic Reconstruction of Articulated Objects. US Patent App. 18/441,589

[11] **M.Z.Irshad**, S.Zakharov, R.Ambrus, V.Guizilini, A.Gaidon, R.Ambrus. NeO 360: Neural Fields for Sparse View Synthesis of Outdoor Scenes. US Patent App. 18/487,956

[12] **M.Z.Irshad**, S.Zakharov, R.Ambrus, A.Gaidon. Implicit Representations for Multi-Object Shape, Appearance and Pose optimization. US Patent App. 17/868,614

[13] **M.Z.Irshad**, T.Kollar, M.Laskey, K.Stone. System and method for Single-shot multi-object 3D shape reconstruction and categorical 6D pose and size estimation. US Patent App.63/243,984

[14] H.Chiu, Z.Seymour, N.C.Mithun, **M.Z.Irshad**, S.Samarasekera, R.Kumar, K.Thopalli. System and method for efficient visual navigation. US Patent App. 63/126,981

Research Projects

Large Behavior Models for Generalist Manipulation

Toyota Research Institute

Research Scientist (1 publication) [LBM]

Spring. 2024 - Fall 2025.

- Co-led and core contributor to multi-task policy learning and post-training efforts.
- Published a 40-page technical report as the first author(s) on the rigorous science behind LBMs
- Worked on co-creating a large foundation model for Dexterous and Generalist Robot Learning

Generative AI for Robotics

Toyota Research Institute

Research Scientist (2 publications) [RoVi-Aug | DiffusionNOCS]

Spring. 2024 - Fall 2024.

- Cross-collaboration with Woven by Toyota on improving symmetric object 6D pose estimation using Diffusion models.
- Collaborated with University of California Berkeley on Zero-shot viewpoint and cross-embodiment aware robot learning.
- 2 papers accepted to CORL 2024 and IROS 2024. Press Coverage by TechXplore.

Neural Radiance Fields for Self-Supervised and Generalizable 3D Representations

Georgia Tech / TRI

PhD & Research Scientist (3 publications) [NeRF-MAE | NeO 360] | MVGD]

Spring. 2023. Spring 2025

- Zero-shot novel view and depth synthesis model trained on 60M multi-view image dataset.
- Innovated a 3D pretraining strategy based on NeRF and masked auto-encoders for 3D scene understanding.
- Improved SOTA on few-view synthesis for unbounded scenes. Proposed an image-conditional triplane representation.
- 2 papers accepted to ECCV 2024 and ICCV'23. U.S. patents applied.

Scaling-Up Camera Calibration for Large-scale Robot Learning Datasets

Toyota Research Institute

Research Scientist (2 publications) [DROID | Open X-Embodiment]

Fall. 2024 - Spring 2025.

- Publically released Posed-DROID; Automatic post-hoc calibration of large scale robotics dataset with robust quality metrics.
- Utilized various foundation models for zero-shot camera calibration; provided 36k good quality camera poses.
- 2 papers accepted to RSS 2024, ICRA 2024. Best paper award at ICRA 2024.

Foundation Models for Zero-shot 3D Navigation and Robotics Manipulation

Toyota Research Institute

Research Scientist (2 publications) [POGS | LEGS

Fall. 2024 - Spring 2025.

- Collaborated with University of California Berkeley on two projects for foundation model distillation into 3D neural fields.
- Semantic foundation distillation enables text-driven navigation and zero-shot object tracking and manipulation.
- 2 papers accepted to IROS 2024 and ICRA 2024

Object-centric 3D Pose, Shape and Appearance Reconstruction

Georgia Tech

PhD & Research Intern (5 publications) [CenterSnap | ShAPO | FSD | CARTO]

Summer 2021 - Spring. 2022

- Proposed a novel single-shot method to reconstruct 3D shape and recover poses of novel object instances in the real world
- Improved performance on 6D pose and size estimation with real-time inference and self-supervised capabilities
- 4 papers accepted to CVPR 2025, ICRA 2024, ECCV 2022 and ICRA'22. U.S. patents applied.

Multimodal AI for Embodied Semantic Perception & Planning

Georgia Tech/TRI

PhD & Research Intern (2 publications) [Robo-VLN | SASRA]

Fall 2020 & Spring 2021

- Proposed hierarchical & semantic transformer for vision-and-language navigation; achieves state-of-the-art (14% SR ↑)
- 2 papers accepted to ICRA'21 and ICPR'22. U.S. patent applied.

Talks

Oct 2025	**Pose Estimation in Robotics: From Object Understanding to Camera Calbration**, ICCV 2025 Worksop on Challenge on Category-Level Object Pose Estimation in the Wild	*Virtual, Hawaii*
July 2025	**Embodied Artificial Intelligence for 3D Perception leveraging Inductive Priors**, GIKI	*Virtual*
Dec 2024	**Learning 3D Robotics Perception using Inductive Priors**, Woven by Toyota	*Tokyo, JP*
Aug 2024	**Towards Embodied 3D Foundation Models**, Habib University	*Karachi, PK*
Apr 2024	**Towards 3D Foundation Models** [Presentation Link], Facebook AI Research	*Bay Area, CA*
Mar 2024	**Neural Fields in Vision and Beyond** [Presentation Link], Stanford Computer Vision Class	*Bay Area, CA*
Jan 2024	**Neural Fields in Robotics and beyond** [Presentation Link], Sanford Robot Perception Class	*Bay Area, CA*
Jul 2023	**Learning Object-Centric Neural 3D Scene Representations**, Robotics and AI Institute	*Boston, MA*
Jun 2023	**Neural Fields in Robotics** [Presentation Link], 3D Deep Learning Reading Group	*Virtual*
Jun 2023	**Learning Object-Centric Neural 3D Scene Representations**, Qualcomm	*San Diego, CA*
Apr 2023	**Learning Object-centric Neural 3D Scene Representations** [Talk Link], Cohere for AI	*Virtual*
Apr 2023	**Learning Object-centric Neural 3D Representations**, Georgia Tech Deep Learning Class	*Atlanta, GA*

Professional Activities

Associate Editor	International Conference on Robotics and Automation (ICRA'26): [Webpage/Program/Call for Papers]
Organizer	Robo3D-VLMs: 3D Vision Language Models for Robotics Manipulation (CVPR'25): [Webpage/Call for Papers]
Organizer	RoboNerF: 1st Workshop On Neural Fields In Robotics (ICRA'24)[Webpage/Program/Accepted Papers]
Reviewer	CVPR'25, Neuips'25, ICLR'25, RSS'25, IROS'25, ICCV'25, RAL'25
Reviewer	ECCV'24, ICLR'24, ICRA'24, CVPR'24
Reviewer	CVPR'23, Neural Fields Workshop CVPR'23, NeurIPS'23, Siggraph'23, ICCV'23
Reviewer	ECCV ' 22, ICRA ' 22, RA-L ' 22
Reviewer	IROS'21, ICRA'21

Skills

Deep Learning	Pytorch, Lightning AI, Tensorflow, Huggingface, AWS (Sagemaker)
Computer Vision	3D Detection, 6D pose estimation, Neural Fields (NeRF), RGB-D Vision, 3D Gaussian Splatting
Machine Learning	Supervised learning, Pretraining, Self-Supervised Learning, Few-shot Learning, Finetuning
Programming	Python, C++, OpenCV, ROS, Linux, Github, LaTeX, Habitat, Habitat, Matterport3D, Gibson

Teaching

Computer Vision EE/CE 452/461

Karachi, PK

Instructor, Habib University

Spring. 2026 (Ongoing)

- Teaching a 3-credit hour undergraduate-level course on the introduction to Computer Vision

Data Structures and Algorithm CS/CE 102/171

Karachi, PK

Instructor, Habib University

Spring. 2026 (Ongoing)

- Teaching a 4-credit hour course (including lab) to undergraduate students at Habib University

Object Oriented Programming and Design Methodologies CS/CE 224/272

Karachi, PK

Instructor, Habib University

Fall. 2025

- Teaching the course to undergraduate students at Habib University

Deep Learning CS7643 *Atlanta, GA*

Graduate Teaching Assistant, Georgia Institute of Technology (Co-taught with Facebook AI): *Spring. 2021*

- Hosting office hours and grading assignments.

Robotics ME 7757 *Atlanta, GA*

Teaching Practicum, Georgia Institute of Technology *Spring. 2021*

- Co-teaching 3 classes, designing homework and exam.

Honors & Awards

2023	**IEEE International Conference on Computer Vision Doctoral Consortium**, ICCV	*France*
2022	**Funding from Toyota Research Institute for PhD**, PhD. at Georgia Tech	*U.S.A*
2018	**ASME RICE Cullimore Scholar**, for M.S at Georgia Tech	*Atlanta, GA*
2018	**1st Place**, Technology Ventures class competition among 12 teams at Georgia Tech	*Atlanta, GA*
2017	**Fulbright International Scholar**, for M.S at Georgia Tech	*U.S.A*
2015	**Distinction/Dean honors roll**, (all semesters) for outstanding academic achievement	*Topi, PK*

Open-Source Software

[1] Awesome Implicit NeRF Robotics [Github], 1350+ stars, 80+ forks.

[2] CenterSnap (Single-Shot Pose and Shape) [Github], 300+ stars, 45+ forks.

[3] NeO 360 (Generalizable NeRF) [Github], 230+ stars, 10 forks.

[4] ShAPO (Implicit Pose, Shape and Appearance of Objects) [Github], 180+ stars, 12 forks.

[5] Open X-Embodiment [Github], 1.2k+ stars, 75+ forks.

[6] DROID Policy Learning [Github], 180+ stars, 16 forks.

[7] Robo-VLN (Robotics Vision-and-Language Navigation [Github], 60+ stars, 8 forks.

[8] Awesome Robotics 3D [Github], 600+ stars, 30+ forks

[9] NeRF-MAE (3D Representation Learning for NeRFs [Github], 100 stars, 3 forks

[10] Articulated Object NeRF [Github], 50 stars, 3 forks.

Advising

PhD. Yunhai Han, Georgia Tech

Intern Mingtong Zhang, Toyota Research Institute – Now PhD at Princeton

M.S Gunjan Chablani, Georgia Tech – Now at Waymo

PhD. Xinan Zhang, Georgia Tech

M.S Shiva Gantha, Georgia Tech – Now R.E. at Matic

M.S Vishnu Jaganathan, Georgia Tech – Now at C3.AI

Fellows Ahnaf Munir, Fatima Fellowship, supported by Huggingface – Now PhD at UCF

Intern Nick Heppert, Toyota Research Institute — Now PhD at U.Frieburg

M.S. Mayank Lunayach, Georgia Tech – Now S.E at Google